

EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	2	"20080147238".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/05 19:03
S2	6022	("700" or "901").clas. and (axis axes) and force and (points set \$points) and (servo control)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 10:42
S3	610	("700" or "901").clas. and (axis axes) and force and (points set \$points) and (servo control) and (generat \$3 with path)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 10:44
S4	48	("700" or "901").clas. and (axis axes) and force and (points set \$points) and (servo control) and (generat \$3 with path) and (sampl\$3 near frequency)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 10:47
S5	1523	joly.in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 14:31
S6	141	joly.in. and force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 14:31

S7	4	joly.in. and force and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 14:31
S8	296	multi\$axis near robot and force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 14:41
S9	220	multi\$axis near robot and force and points	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 14:41
S10	10	multi\$axis near robot and force and points and tangent	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 14:41
S11	2	"4967127".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 15:07
S12	2	"20040093119".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 15:10
S13	2	"20030200042".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 15:10
S14	629	robot same (axis or joint) and tangent	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 19:59

S15	74	robot same (axis or joint) and (tangent same (compar\$4 or difference))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/01/12 20:00
S16	194	(robot\$3 or arm) and ((minimiz\$3 minimization reduc\$4 lower\$3 eliminat\$3) with difference with (point set\$point) with force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/08/09 19:48
S17	7	(robot\$3 or arm) and ((minimiz\$3 minimization reduc\$4 lower\$3 eliminat\$3) with difference with (point set\$point) with force with project\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/08/09 19:49

EAST Search History (I nterference)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	((path near generator) same robot same (projection near force) same (tangent near path) same (movement near set\$point)). clm.	USPAT; UPAD	OR	ON	2010/08/25 08:33

8/ 25/ 2010 8:36:54 AM

C:\ Documents and Settings\ rking2\ My Documents\ EAST\ Workspaces\ Method and Apparatus For Controlling Displacements of a Moving Portion of a Multi-Axis Robot.wsp